

On geodetic sets of graphs

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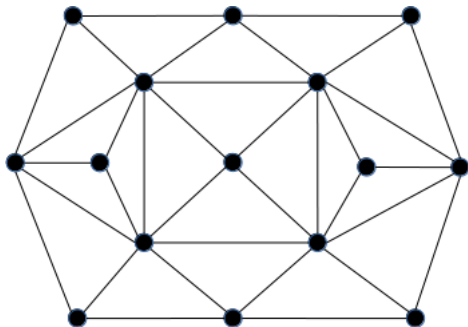
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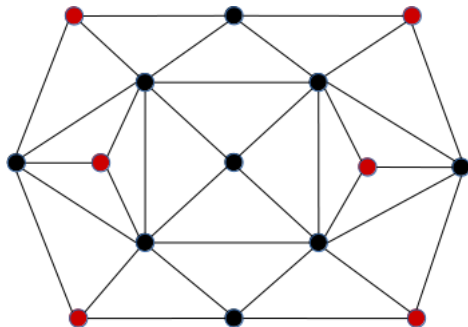
***Joint work with Florent Foucaud, Harmender Gahlawat, Subir Kumar Ghosh, and Bodhayan Roy.

A simplified practical problem



City road network

A simplified practical problem



City road network

- Open **minimum** number of new bus terminals such that all other cities are "**covered**".
- **Assumption**: Buses follow the **shortest path** between the terminals.

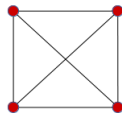
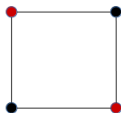
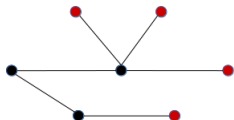
Definition

A set of vertices S of a graph G is a *geodetic set* if each vertex in $V(G) \setminus S$ lies in some *shortest path* between some pair of vertices in S .

Minimum Geodetic Set

INPUT: An undirected graph G .

OUTPUT: A geodetic set of minimum cardinality.



Examples

Computing conundrum

Simplified practical problem = Hard theoretical problem.

Why I got interested in this topic

Algorithmic results before 2018

NP-hard: Chordal graphs, bipartite graphs, chordal bipartite graphs, co-bipartite graphs.

Polynomial time algorithms: Distance hereditary graphs, split graphs, ptolemaic graphs, outer-planar graphs, proper interval graphs.

Probably many (easy) open questions !! 😊

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Important questions

Question 1: Minimum Geodetic Set problem on **planar** graphs.

Question 2: Minimum Geodetic Set problem on **interval** graphs.

I started to work on the above from 2017.

Indo-French Meet 2019 @ (ISI, RKMVERI)

Thanks to **AGROHO (MA/IFCAM/18/39)** and **HOSIGRA (ANR-17-CE40-0022)** projects.

Éric Sopena , Théo Pierron, Florent Foucaud, Julien Bensmail.

Subir Kumar Ghosh, Sandip Das, Sagnik Sen, Bodhayan Roy, Joydeep Mukherjee, Uma kant Sahoo, D.C, Harmendar, Shubhadeep Ranjan Dev, Sanjana Dey, Arun Kumar Das.

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Hardness and Approximation for the Geodetic Set Problem in Some Graph Classes. D.C., Florent Foucaud, Harmender Gahlawat, Subir Kumar Ghosh, Bodhayan Roy: **CALDAM 2020.**

Our results

- NP-hardness for planar graphs and line graphs.
- $O(\log n)$ -hard on graphs with an universal vertex.
- $O(n^{\frac{1}{3}} \log n)$ -approximation algorithm on general graphs.
- 3-approximation algorithm on solid grids.

Some proof ideas !!

- NP-hardness for planar graphs.

► Reduction from DOMINATING SET of planar graphs.

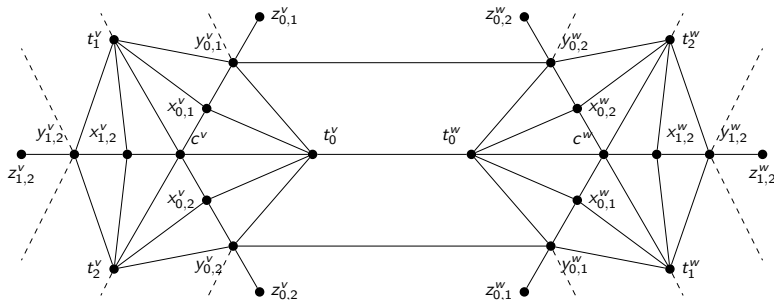


Figure: Here, two vertex gadgets G_v, G_w are depicted, with v and w adjacent in G . Dashed lines represent potential edges to other vertex-gadgets.

Some proof ideas !!

- $O(n^{\frac{1}{3}} \log n)$ -approximation algorithm on general graphs.
- ▶ Reduction to Minimum Rainbow Subgraph problem.

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Minimum Rainbow Subgraph

INPUT: An undirected edge-colored graph G .

OUTPUT: A subgraph containing edges of all colors with minimum number of vertices.

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Minimum Rainbow Subgraph

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OUTPUT: A subgraph containing edges of all colors with minimum number of vertices.

- ▶ Given a graph G , construct an edge-colored graph H as follows.
- ▶ If w lies in some shortest path between u, v in G , then put an edge having color “ w ” between u, v in H .

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Minimum Rainbow Subgraph

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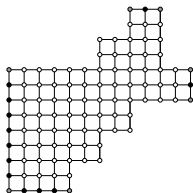
OUTPUT: A subgraph containing edges of all colors with minimum number of vertices.

- ▶ Given a graph G , construct an edge-colored graph H as follows.
- ▶ If w lies in some shortest path between u, v in G , then put an edge having color “ w ” between u, v in H .
- ▶ Apply known $O(n^{\frac{1}{3}} \log n)$ -approximation algorithm on Minimum Rainbow Subgraph problem.

*On the Approximability of the Minimum Rainbow Subgraph Problem and Other Related Problems. Sumedh Tirodkar, Sundar Vishwanathan. ISAAC 2015.

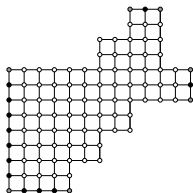
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- 3-approximation algorithm on solid grids.



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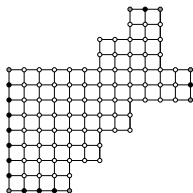
- 3-approximation algorithm on solid grids.



- A path P of a solid grid is a corner path if (i) no vertex of P is a cut vertex, (ii) both end-vertices of P have degree 2, and (iii) all vertices except the end-vertices of P have degree 3.

Some proof ideas !!

- 3-approximation algorithm on solid grids.

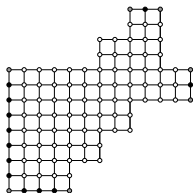


- A path P of a solid grid is a corner path if (i) no vertex of P is a cut vertex, (ii) both end-vertices of P have degree 2, and (iii) all vertices except the end-vertices of P have degree 3.

Lemma: Any geodetic set must contain (i) all pendent vertices and (ii) at least one vertex from each corner path.

Some proof ideas !!

- 3-approximation algorithm on solid grids.



- A path P of a solid grid is a **corner path** if (i) **no vertex** of P is a **cut vertex**, (ii) both **end-vertices** of P have degree 2, and (iii) all vertices **except** the end-vertices of P have degree 3.

Lemma: Any geodetic set must contain (i) all **pendent** vertices and (ii) at least **one** vertex from each **corner path**.

Our approximation algorithm: Select all **pendent** vertices and **both end-vertices** of each **corner path**. 😊

The future

- Polynomial time optimal algorithms on **solid** grids.
- Polynomial time optimal algorithms on **partial** grids.
- Polynomial time optimal algorithms on **interval** graphs.
- FPT or approximation algorithms on **planar** graphs.
- FPT or approximation algorithms on **chordal** graphs.
- Approximation algorithms on **diameter 2** graphs.

The future

- Polynomial time optimal algorithms on **solid** grids. (Done)
- Polynomial time optimal algorithms on **partial** grids. (Impossible*)
- Polynomial time optimal algorithms on **interval** graphs. (Impossible*)

* Assuming $P \neq NP$.

The future

- Polynomial time optimal algorithms on solid grids. (Done)
- Polynomial time optimal algorithms on partial grids. (Impossible*)
- Polynomial time optimal algorithms on interval graphs. (Impossible*)

* Assuming $P \neq NP$.

- FPT or approximation algorithms on planar graphs ?
- FPT or approximation algorithms on chordal graphs ?
- Approximation algorithms on diameter 2 graphs ?

Thank you !!